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(Based on PTO 01-08 version)

Substitute for form 1449/PTO INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Use as many sheets as necessary)			Complete if Known		
			Application Number	10/660,747	
			Filing Date	Sept. 12, 2003	
			First Named Inventor	Thomas D. Williams	
			Art Unit	2179	
			Examiner Name	N. Augustine	
Sheet	1	of	1	Attorney Docket Number	I2101.001/P001

U.S. PATENT DOCUMENTS					
Examiner Initials*	Cite No. ¹	Document Number	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
		Number-Kind Code ² (if known)			
	A1	6,219,444 B1	04/17/2001	Shashua et al.	

FOREIGN PATENT DOCUMENTS							
Examiner Initials*	Cite No. ¹	Foreign Patent Document		Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages Or Relevant Figures Appear	T ⁶
		Country Code ³ -Number ⁴ -Kind Code ⁵ (if known)					

Examiner Signature		Date Considered	
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NON PATENT LITERATURE DOCUMENTS			
Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
	C1	SHASHUA, A. et al., "Trilinearity of Perspective Views and its Associated Tensor," Institute of Computer Science, June 1995, Hebrew University of Jerusalem.	
	C2	AVIDAN, S. et al., "Novel View Synthesis by Cascading Trilinear Tensors," IEEE Transactions on Visualization and Computer Graphics, Vol. 4, No. 4, pp. 293-306, October-December, 1998.	
	C3	FAUGERAS, O. et al., "What can two images tell us about a third one?", INRIA, Programme 4 - Robotique, image et vision, Projet Robotvis, pp. 1-23, July 1993, Sophia Antipolis, France.	
	C4	BARRETT, E.B. et al., "Some Invariant Linear Methods in Photogrammetry and Model-Matching," IEEE, O-8186-2855, pp. 122-128, March 1992.	

Examiner Signature		Date Considered	
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